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REACT to Cyber-Physical Attacks on the Power Grid

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Infrastructure Networks

- ❑ Almost all infrastructure networks are monitored and controlled by Supervisory Control And Data Acquisition Systems (SCADA)
- ❑ The physical components of these networks along with their control network form a *cyber-physical system*
- ❑ Due to their direct control of the infrastructure networks, SCADA systems have been the main targets of cyber attacks (e.g., Stuxnet virus)



New York State ISO Control Room

Attacks and Failures in Power Systems

Physical Attacks



Power Grid
Physical Infrastructure



Cyber Attacks

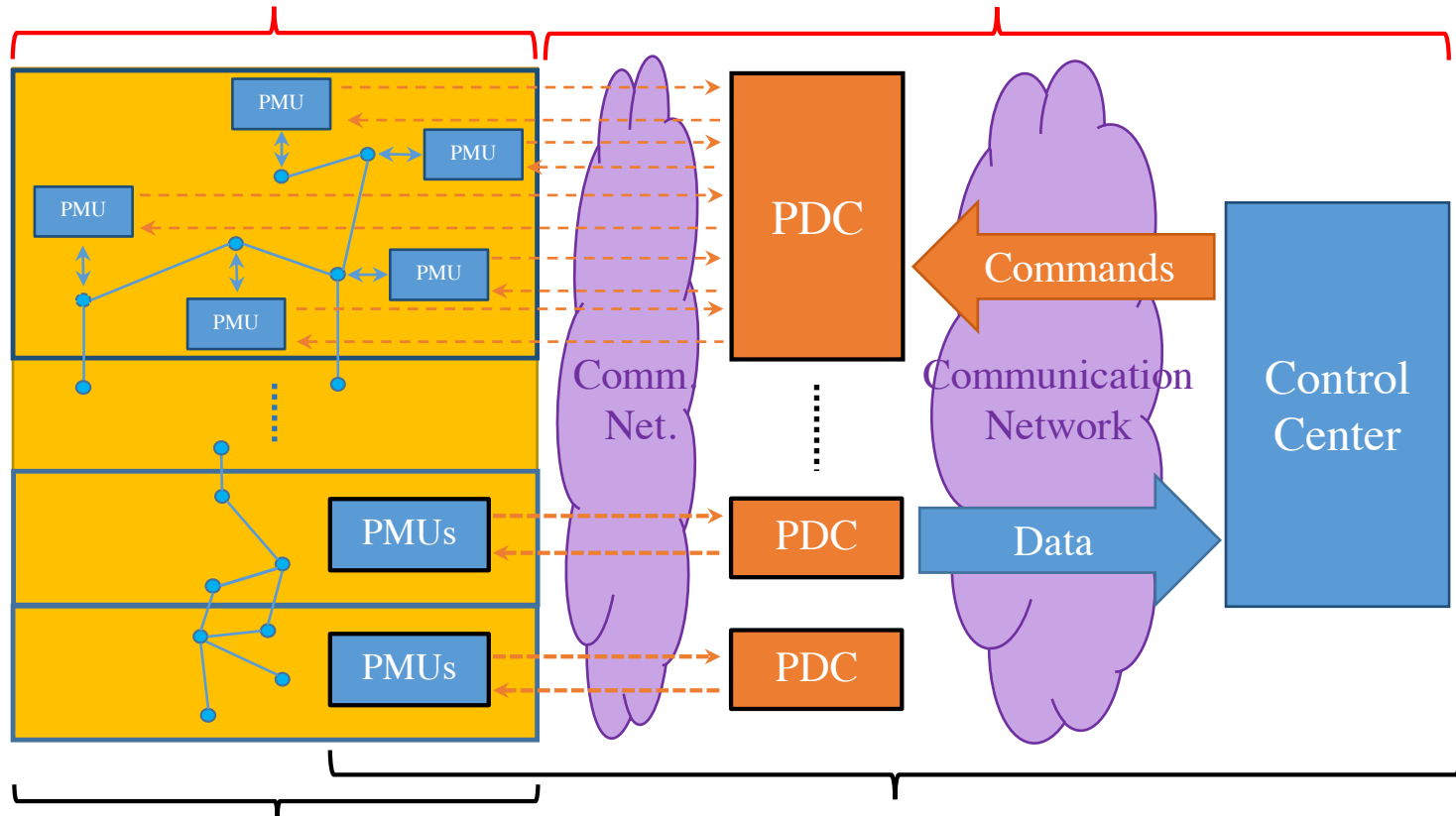


Supervisory Control and Data
Acquisition (SCADA) system

Components of Power Grid SCADA

Physical Attack Target

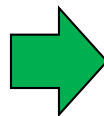
Cyber Attack Target



Power Grid
Physical Infrastructure

Supervisory Control and Data
Acquisition (SCADA) system

PMU: Phasor Measurement Unit
PDC: Phasor Data Concentrators



IED: Intelligent Electronic Devices
DC: Data Concentrators

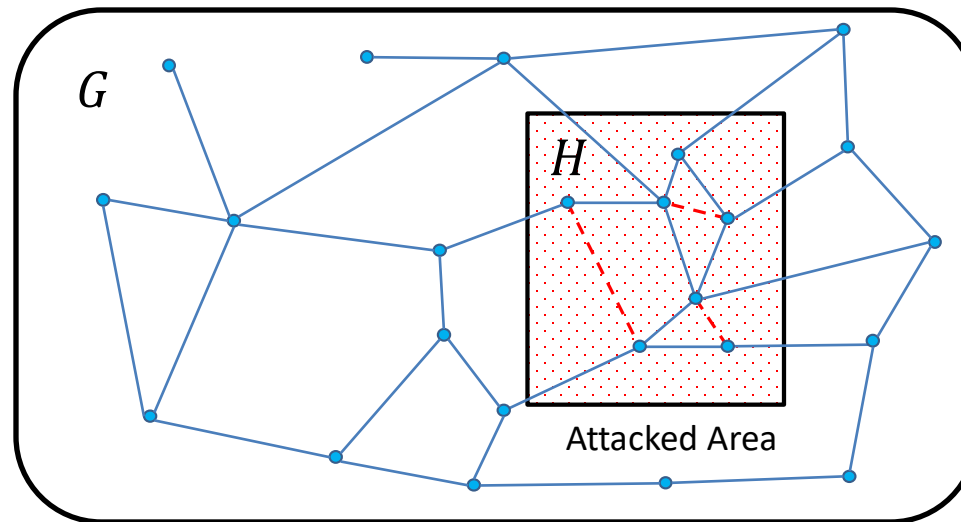
Cyber Attack on the Ukrainian Grid

- ❑ Unplugged 225,000 people from the Ukrainian electricity grid in December 2015
 - Steal credentials for accessing the SCADA system, *before June 2015*
 - Explore of SCADA system and attack planning, *June-Dec. 2015*
 - Remotely operate circuit breakers, *day of attack*
 - Phone jamming attacks keeps operators unaware, *day of attack*
- ❑ “An attacker can simply replay, modify, and spoof the traffic to SCADA devices”



Attack Model

- ❑ An adversary attacks the grid by
 - Manipulating the measurements (cyber)
 - **Block** the measurements
 - **Falsify** the measurements (false data injection)
 - Disconnecting lines within the attacked area (physical)
- **Goal:** Efficiently detect the attacked area and the disconnected lines to avoid further failures



AC Power Flows

□ Present the grid by a connected graph $G = (N, E)$

□ In the phasor domain

□ $V_i = |V_i|e^{j\theta_i}$

$|V_i|$ is the Voltage magnitude

θ_i is the phase angle

□ Transmission line (i, k) is characterized by series admittance $y_{ik} = g_{ik} + jb_{ik}$

□ The active and reactive power flows:

$$P_{ik} = |V_i|^2 g_{ik} - |V_i||V_k|g_{ik} \cos \theta_{ik} - |V_i||V_k|b_{ik} \sin \theta_{ik}$$

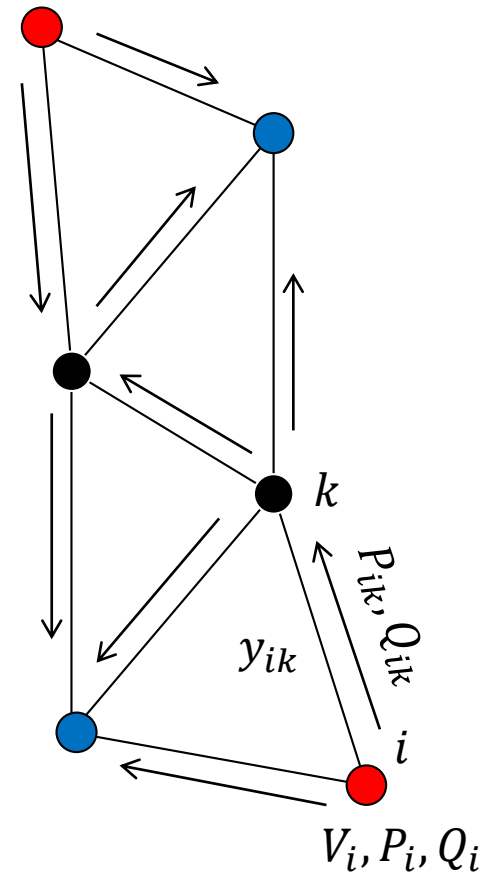
$$Q_{ik} = -|V_i|^2 b_{ik} + |V_i||V_k|b_{ik} \cos \theta_{ik} - |V_i||V_k|g_{ik} \sin \theta_{ik}$$

and $\theta_{ik} = \theta_i - \theta_k$

□ Active and reactive power at node i :

$$P_i = \sum P_{ik}, Q_i = \sum Q_{ik}$$

□ Given a subset of P, Q, V values, compute the rest \rightarrow nonlinear and not unique



● Load ($P_i < 0$)

● Generator ($P_i > 0$)

Power Flows - DC Approximation

□ In the stable state of the system

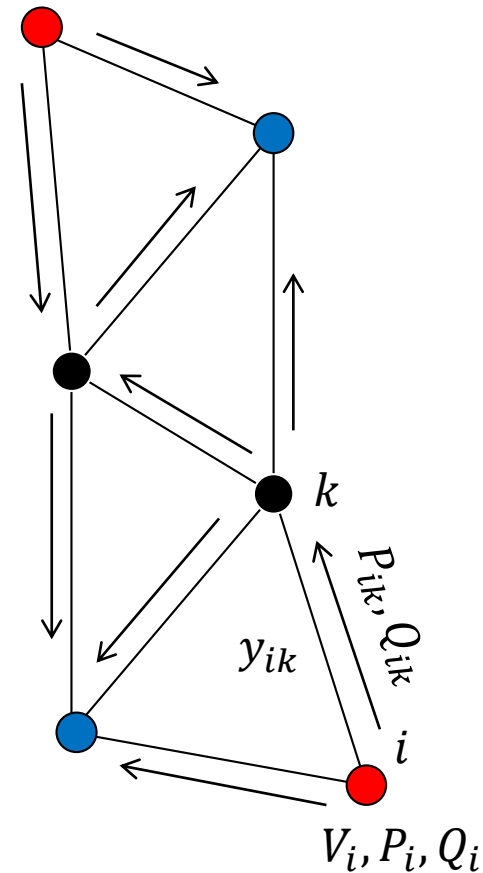
- $|V_i| \approx 1 \text{ p.u. for all } i$
- $\left| \frac{g_{ik}}{b_{ik}} \right| \ll 1 \text{ for all lines} \Rightarrow y_{ik} \approx ib_{ik}$
- $\theta_{ik} \ll 1 \Rightarrow \cos(\theta_{ik}) \approx 1 \text{ and } \sin(\theta_{ik}) \approx \theta_{ik}$

□ The power flow equations reduce to

$$f_{ik} := P_{ik} = -b_{ik}(\theta_i - \theta_k)$$

$$\sum_k P_{ik} = P_i$$

□ The DC power flows only considers active powers



- Load ($P_i < 0$)
- Generator ($P_i > 0$)

DC Power Flows (Matrix Form)

□ The DC power flow can be written in matrix form:

$$YD^T \vec{\theta} = \vec{f}$$

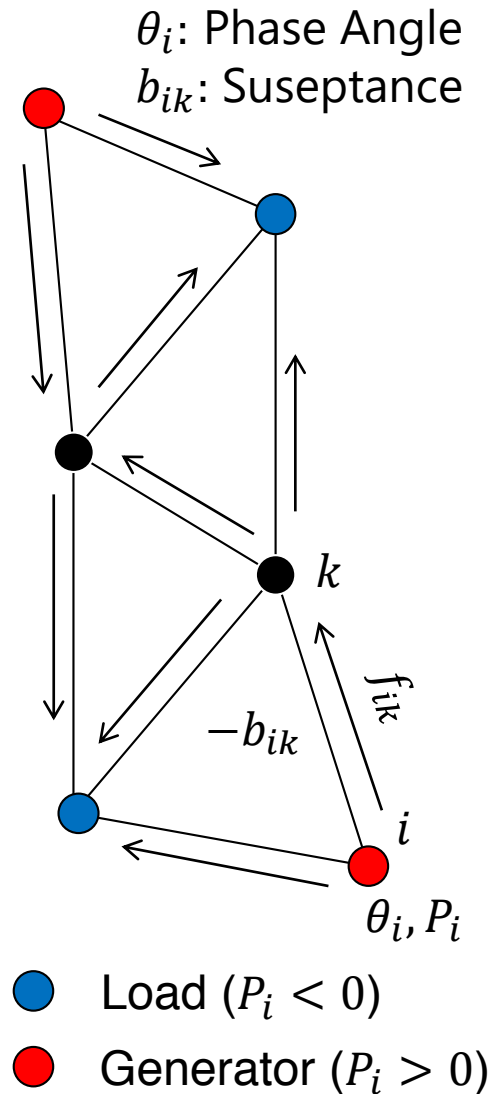
$$A\vec{\theta} = \vec{p}$$

$D \in \{-1, 0, 1\}^{n \times m}$: the **incidence matrix** of the grid:

$$d_{ij} = \begin{cases} 0, & \text{if } e_j \text{ is not incident to node } i, \\ 1, & \text{if } e_j \text{ is coming out of node } i, \\ -1, & \text{if } e_j \text{ is going into node } i, \end{cases}$$

$Y \in \mathbb{R}^{m \times m}$: the diagonal matrix of susceptance values,

and $A = DYD^T$: the **admittance matrix** of the grid



Assumptions and Objective

□ Assume that the phase angles $\vec{\theta}$ are measured directly at all the nodes

□ Correct phase angles after the attack: $\vec{\theta}' = \begin{bmatrix} \vec{\theta}'_H \\ \vec{\theta}'_{\bar{H}} \end{bmatrix}$

□ Measured phase angles after the attack: $\vec{\theta}^* = \begin{bmatrix} \vec{\theta}^*_H \\ \vec{\theta}^*_{\bar{H}} \end{bmatrix}$

➤ $\vec{\theta}^*_{\bar{H}} = \vec{\theta}'_{\bar{H}}$

Objective: Use the measurements after the attack ($\vec{\theta}^*$) and the information before attack ($A, \vec{\theta}$) to:

➤ Detect the attack area (H)

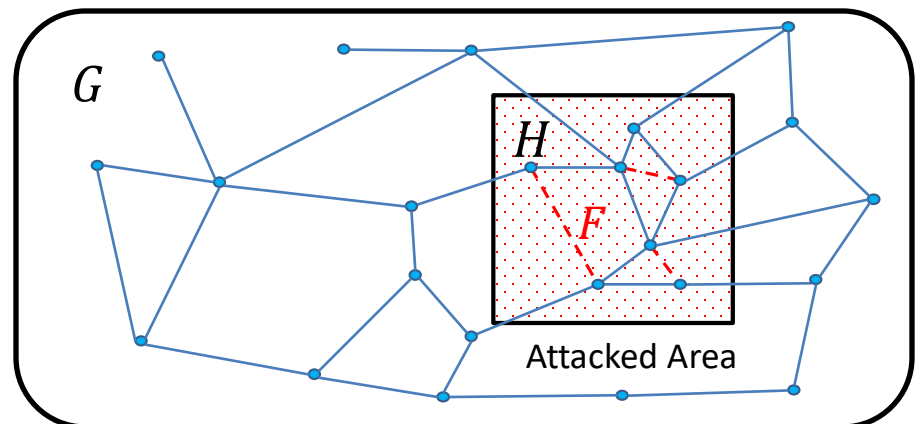
➤ Detect the disconnected lines (F)

H : an induced subgraph of G that represents the attacked area

\bar{H} : $G \setminus H$

F : Set of failed lines

O' : The value of O after an attack



False Data Injection

□ Assume two types of *data attacks*:

- **Data distortion:** the attacker adds large noise to the measurements coming from the attacked area:

$$\vec{\theta}_H^* = \vec{\theta}_H' + \vec{z}$$

- **Data replay:** the attacker replays measurements from previous hours/days instead of the actual measurements coming from the attacked area:

$$\vec{\theta}_H^* = \vec{\theta}_H''$$

in which $A\vec{\theta}'' = \vec{p}''$ and $\vec{p}_H'' = \vec{p}_H$.

□ Measurements remain **locally consistent** after a *replay attack*

Outline

- ❑ Hardness
- ❑ Attacked Area Approximation
 - Data distortion
 - Data replay
 - ATtacked Area Containment (ATAC) module
- ❑ Line Failures Detection
- ❑ REcurrent Attack Containment and deTection (REACT) Algorithm
- ❑ Numerical Results

Hardness

Lemma. Given A , $\vec{\theta}$ and $\vec{\theta}'$, it is strongly NP-hard to determine if there exists a set of line failures F such that:

$$A^{(F)} \vec{\theta}' = A \vec{\theta}$$

□ Reduction from 3-partition problem

Lemma. Given A , $\vec{\theta}$, H and $\vec{\theta}'_H$, it is strongly NP-hard to determine if there exists a set of line failures F in H and a vector $\vec{\theta}'_H$ such that

$$A^{(F)} \begin{bmatrix} \vec{\theta}'_H \\ \vec{\theta}'_{\bar{H}} \end{bmatrix} = A \vec{\theta}$$

Lemma. Given A , $\vec{\theta}$ and $\vec{\theta}^*$, it is strongly NP-hard to determine if there exists a subgraph H_0 with $|V_{H_0}| \leq |V|/2$, set of line failures F in H_0 , and a vector $\vec{\theta}'_{H_0}$ such that

$$A^{(F)} \begin{bmatrix} \vec{\theta}'_{H_0} \\ \vec{\theta}^*_{\bar{H}_0} \end{bmatrix} = A \vec{\theta}$$

Attacked Area Approximation

Data Distortion Attack

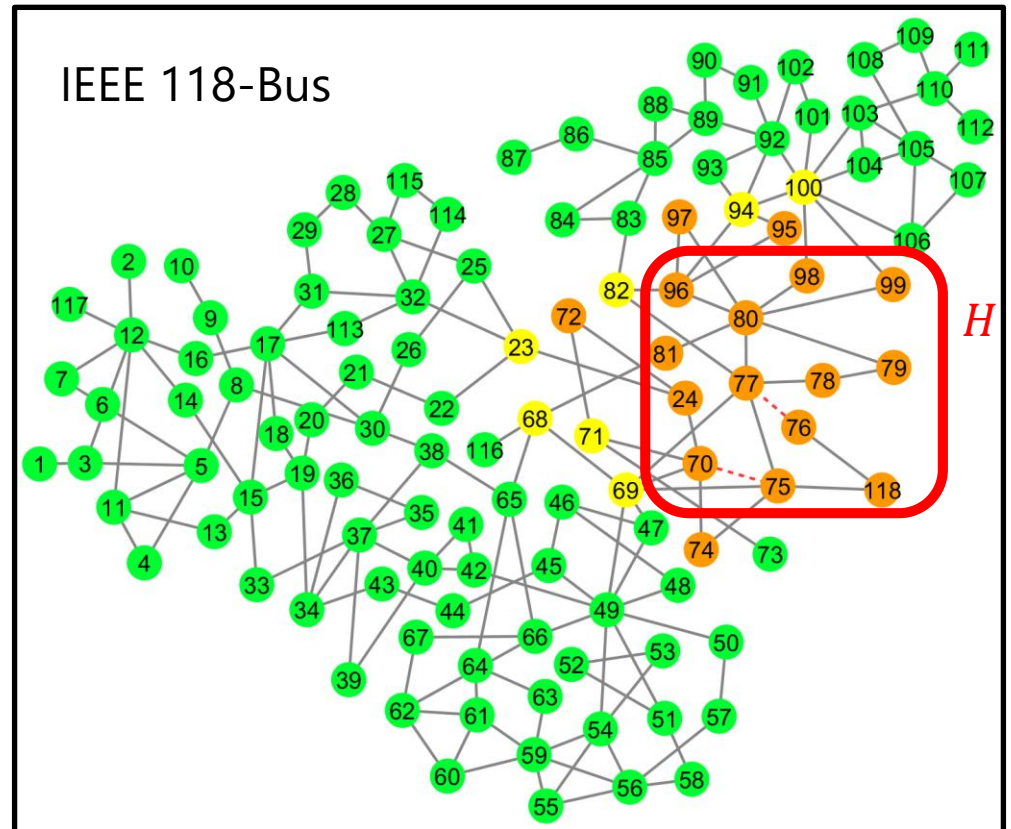
- For any $i \in \text{int}(\bar{H}), A_i \vec{\theta}^* = p_i$
 - For any $i \in V \setminus \text{int}(\bar{H}), A_i \vec{\theta}^* \neq p_i$
- $\text{int}(\bar{H}) = V \setminus \text{supp}(A\vec{\theta}^* - \vec{p})$
- $S_0 := G[\text{supp}(A\vec{\theta}^* - \vec{p})]$
 - $V_H \subseteq \text{int}(S_0)$

$\text{int}(\bar{H}) \rightarrow$ ●

$S_0 \rightarrow$ ● ●

$\text{int}(S_0) \rightarrow$ ●

$\text{int}(S) :=$ nodes in S such that their neighbors are also in S



Data Replay Attack

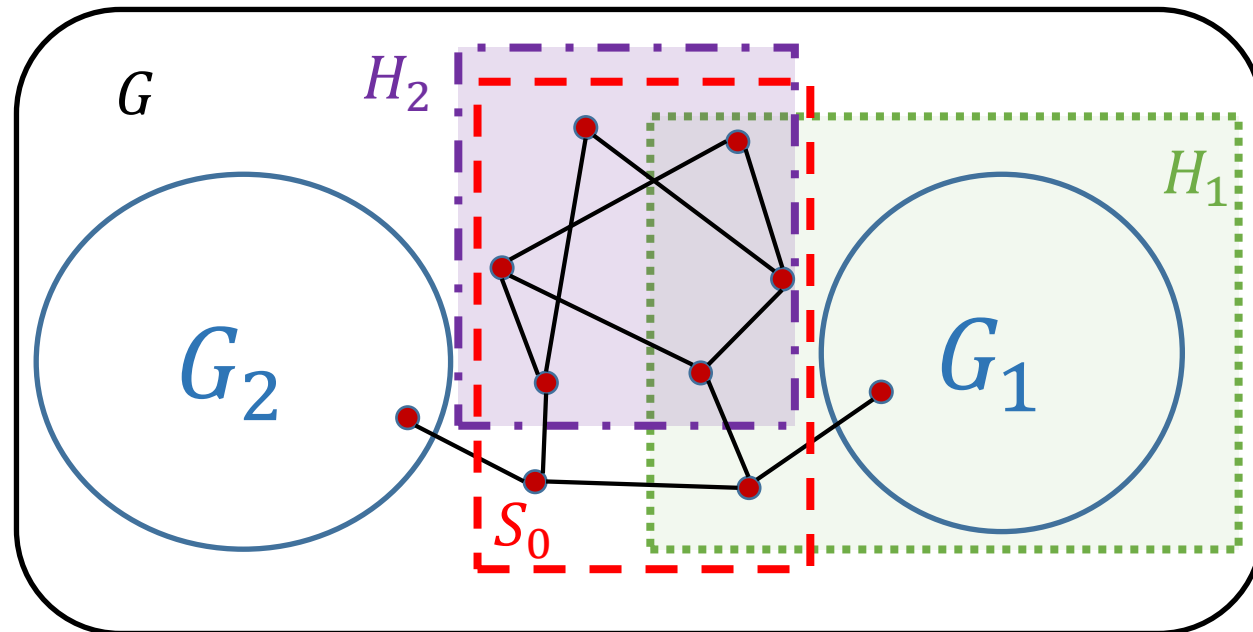
- ❑ Detecting the attacked area is more challenging
 - ❑ For any $i \in \text{int}(\bar{H}) \cup \text{int}(H)$, $A_i \vec{\theta}^* = p_i$
 - ❑ For any $i \in \partial(\bar{H}) \cup \partial(H)$, $A_i \vec{\theta}^* \neq p_i$
- $\text{supp}(A\vec{\theta}^* - \vec{p}) = \partial(H) \cup \partial(\bar{H})$
-
- ❑ $S_0 := G[\text{supp}(A\vec{\theta}^* - \vec{p})]$ does not contain the attacked area in this case

Data replay attack

Data distortion attack

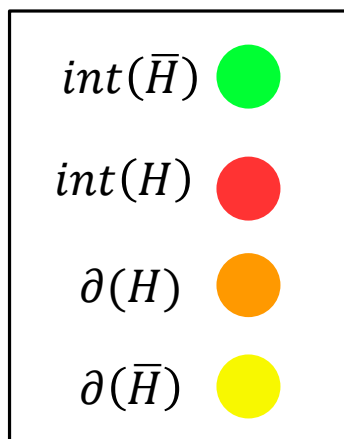
$\text{int}(S) :=$ nodes in S that
their neighbors are also
in S

$\partial(S) :=$ nodes in S that
have neighbors also in \bar{S}



ATtacked Area Containment (ATAC)

- Provide multiple areas that may contain the attacked area



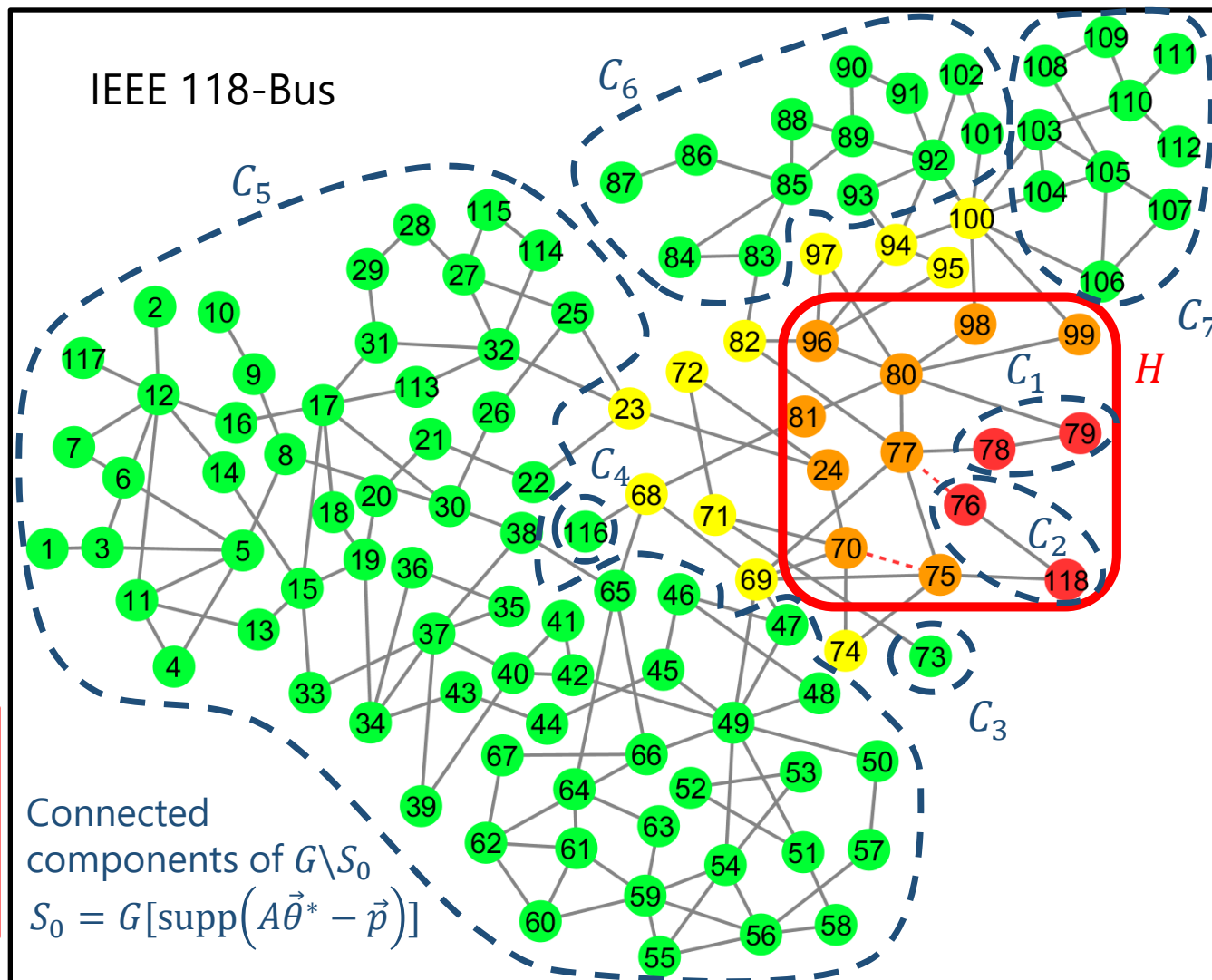
$$G_1 := C_1 \cup C_2$$

$$G_2 := C_4 \cup C_5$$

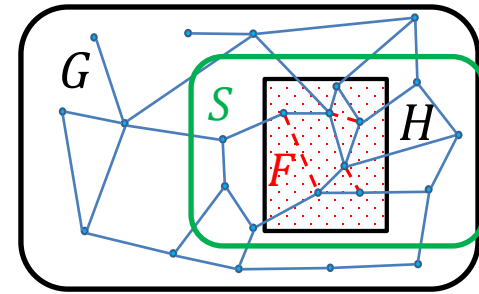
$$G_3 := C_3$$

$$G_4 := C_6 \cup C_7$$

At least one of the $S_0, S_i := G \setminus G_i$ contain the attacked area



Line Failures Detection



$\bar{S}: G \setminus S$

O' : The value of O after an attack

O^* : The modified value of O after an attack

Assume S_0, S_1, \dots, S_t are the subgraphs from ATAC

Assume that S contains $H \rightarrow \vec{\theta}_{\bar{S}}^* = \vec{\theta}'_{\bar{S}}$

Brute force search algorithm

$$\min_{F, \vec{y}} ||A_{G|\bar{S}} \vec{\theta}_{\bar{S}}^* + A_{G|S}^{(F)} \vec{y} - \vec{p}||_2$$

Not efficient \rightarrow specially that we don't know if S contains the attacked area or not

Solution \vec{x} and \vec{y} to the following linear program can detect the phase angles and line failures

Fewest number of line failures \rightarrow

$$\min ||\vec{x}||_1 \text{ s.t.}$$

$$A_{S|G}(\vec{\theta} - \vec{\theta}') = D_S \vec{x} \rightarrow A_{S|S}(\vec{\theta}_S - \vec{y}) + A_{S|\bar{S}}(\vec{\theta}_{\bar{S}} - \vec{\theta}_{\bar{S}}^*) = D_S \vec{x}$$

$$A_{\bar{S}|G}(\vec{\theta} - \vec{\theta}') = 0 \rightarrow A_{\bar{S}|S}(\vec{\theta}_S - \vec{y}) + A_{\bar{S}|\bar{S}}(\vec{\theta}_{\bar{S}} - \vec{\theta}_{\bar{S}}^*) = 0$$

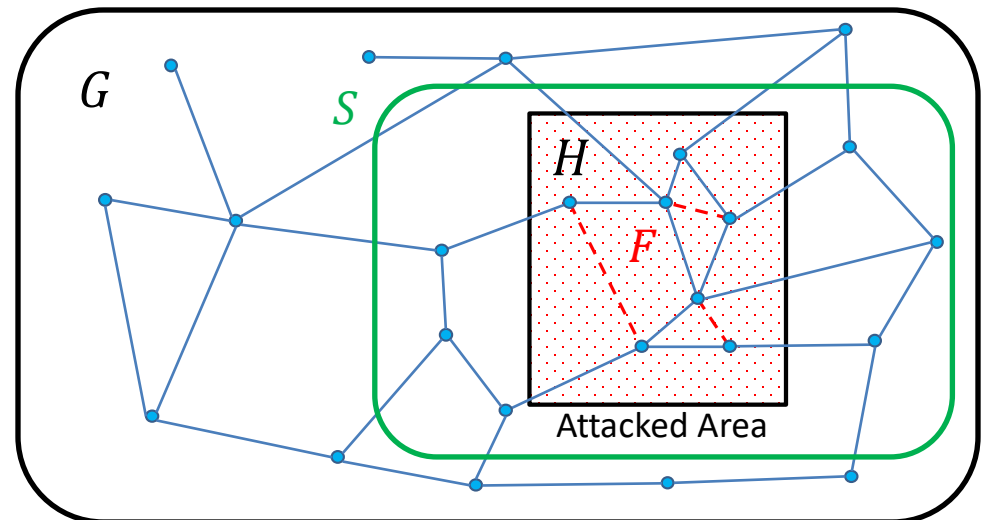
(*)

under some conditions, $\text{supp}(\vec{x}) = F$ and $\vec{y} = \vec{\theta}'_S$.

Conditions and Limitations

External Conditions	Internal Conditions	Attack Constraints
Matching	Acyclic	None
Matching	Planar	Less than half of the edges in each cycle are failed
Partial Matching	Acyclic	Less than half of the edges connected to an internal node are failed
Partial Matching	Planar	Two above conditions

- Since at the time of a data replay attack, S might be much **larger** than H , in most of the cases S may not have the above conditions



Use Random Weights

- For a good diagonal matrix of random weights W , the solution to the following LP detects the line failures

$$\begin{aligned}
 & \min \| W \vec{x} \|_1 \quad s. t. \\
 & A_{S|S}(\vec{\theta}_S - \vec{y}) + A_{S|\bar{S}}(\vec{\theta}_{\bar{S}} - \vec{\theta}_{\bar{S}}^*) = D_S \vec{x} \\
 & A_{\bar{S}|S}(\vec{\theta}_S - \vec{y}) + A_{\bar{S}|\bar{S}}(\vec{\theta}_{\bar{S}} - \vec{\theta}_{\bar{S}}^*) = 0
 \end{aligned} \quad (**)$$

- Confidence of the solution

$$c(F, \vec{y}) := \left(1 - \|A_{G|\bar{S}}\vec{\theta}_{\bar{S}}^* + A_{G|S}^{(F)}\vec{y} - \vec{p}\|_2 / \|\vec{p}\|_2 \right) \times 100$$

- Generate random weights, solve (**)
 - check if for $F = \text{supp}(\vec{x})$ and \vec{y} , $\|A_{G|\bar{S}}\vec{\theta}_{\bar{S}}^* + A_{G|S}^{(F)}\vec{y} - \vec{p}\|_2$ is small enough
 - if not, regenerate W and solve (**)
 - One can prove that in some cases, a good W can be obtained in *expected polynomial time* \rightarrow details in the paper

REACT Algorithm

REcurrent Attack Containment and deTection (REACT)

1. Obtain S_0, S_1, \dots, S_t using the ATAC module
2. For each $i = 1$ to t , compute $S = G[\text{int}(S_i)]$
3. If $(**)$ is not feasible go to the next i
4. While $c(F, \vec{y}) < 99.9$ and *counter* $< T$
5. Generate a random weight matrix W
6. Solve $(**)$
7. Return a solution with the highest confidence

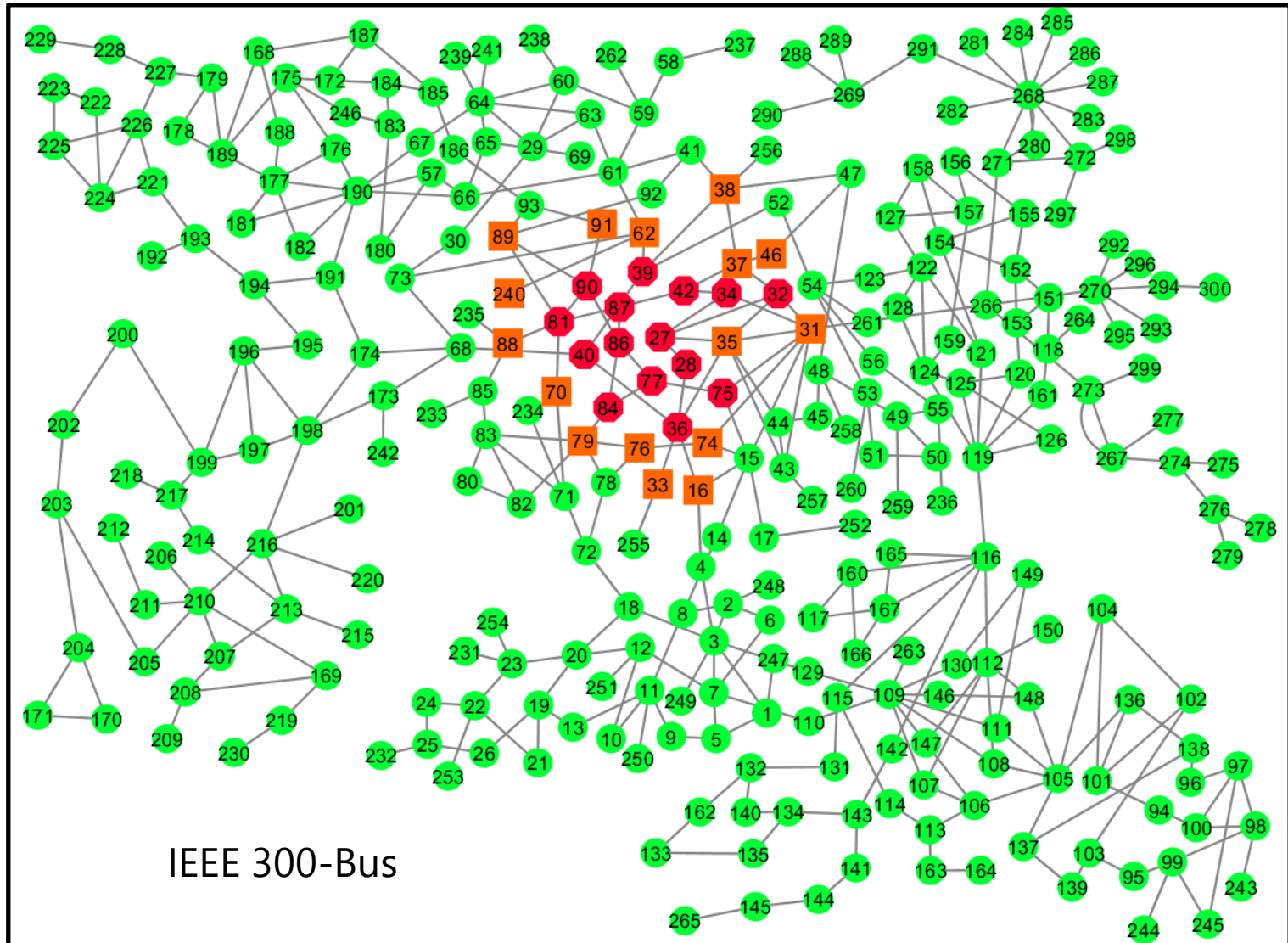
$$\min \| W \vec{x} \|_1 \quad s. t.$$

$$A_{S|S}(\vec{\theta}_S - \vec{y}) + A_{S|\bar{S}}(\vec{\theta}_{\bar{S}} - \vec{\theta}_{\bar{S}}^*) = D_S \vec{x} \quad (**)$$

$$A_{\bar{S}|S}(\vec{\theta}_S - \vec{y}) + A_{\bar{S}|\bar{S}}(\vec{\theta}_{\bar{S}} - \vec{\theta}_{\bar{S}}^*) = 0$$

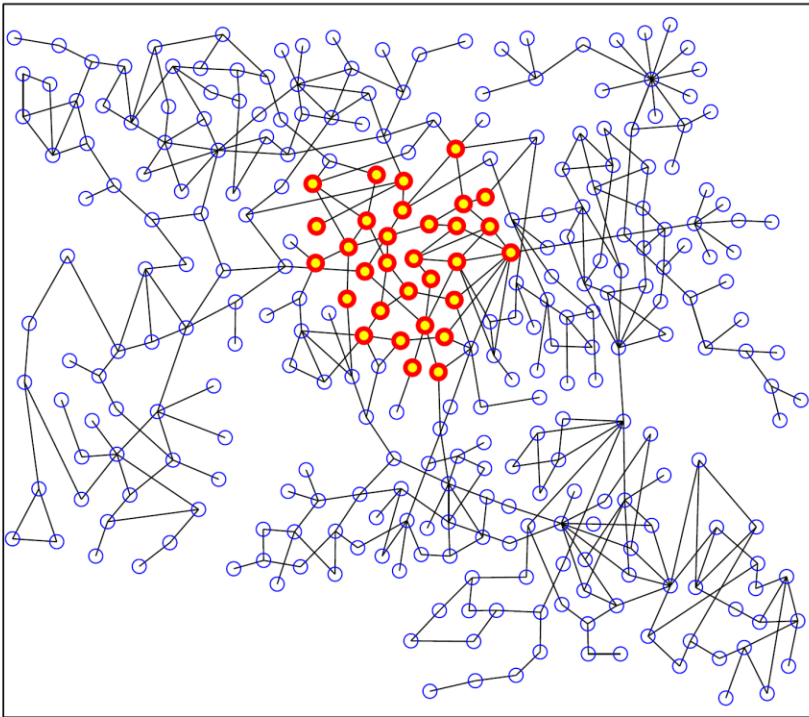
Numerical Results

- Two attacked areas: one with 31 nodes and the other with 15 nodes

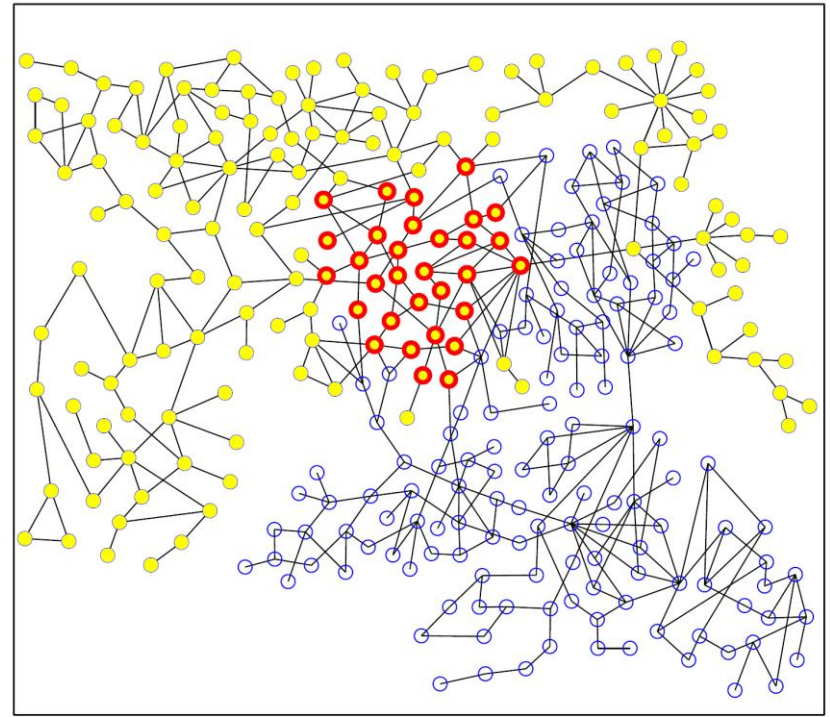


Data Distortion vs. Data Replay

- ❑ Difficulty in detecting the attacked area after a data replay attack



(a) Data Distortion Attack

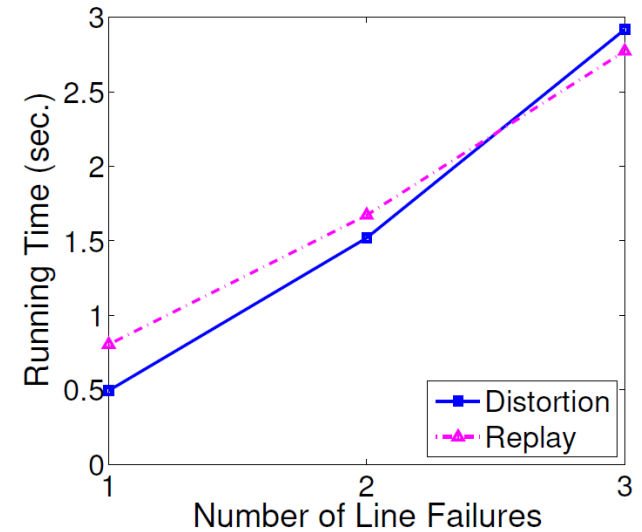
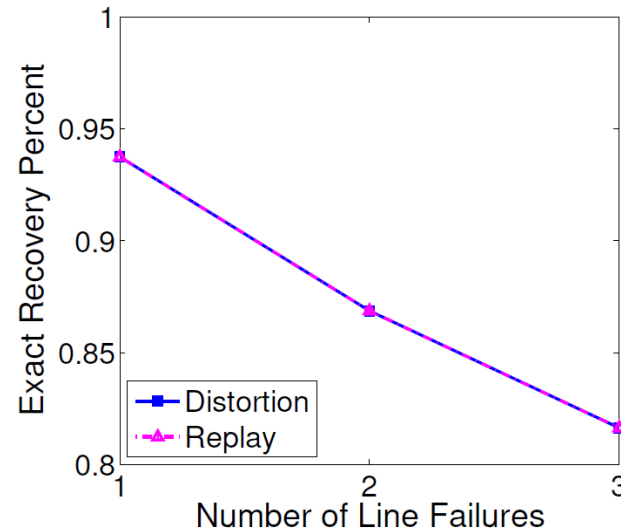


(b) Data Replay Attack

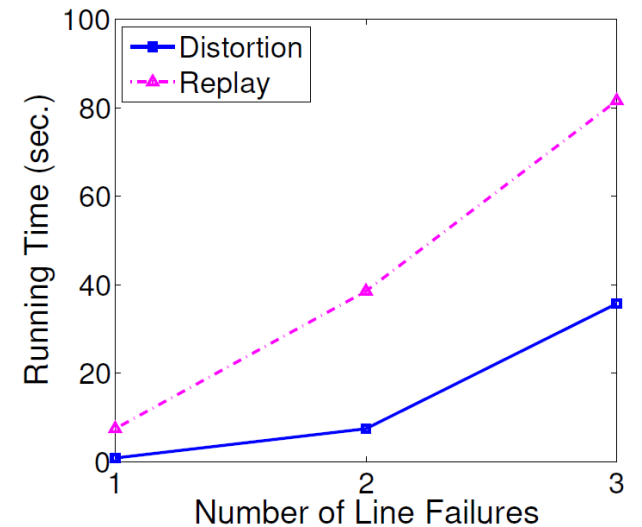
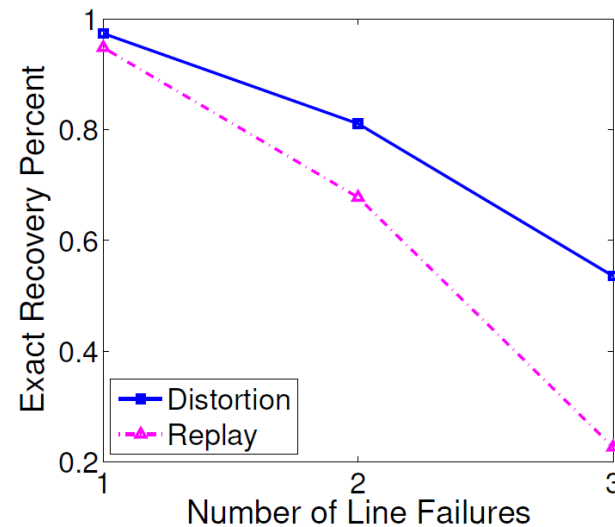
Data Distortion vs. Data Replay

□ $T = 20$

Smaller
Attacked Area



Larger
Attacked Area



Conclusions

- ❑ Modeled cyber-physical attacks on the power grid
 - ❑ Studied hardness
 - ❑ Showed that in general replay attacks (or more sophisticated data attacks) are harder to deal with
 - ❑ Provided a stochastic REACT algorithm to detect the attacked area and line failures → trade-off between accuracy and running time
-
- Extension to the AC power flow model
 - Extension to the noisy scenarios

Saleh Soltan, Gil Zussman, "EXPOSE the Line Failures following a Cyber-Physical Attack on the Power Grid", to appear in IEEE Transactions on Control of Network Systems, 2018.

S. Soltan, P. Mittal, and H. V. Poor, "Bayesian Regression for Robust Power Grid State Estimation Following a Cyber-Physical Attack," to appear in Proc. IEEE PES-GM'18, Aug. 2018.



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Thank You!

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